

# Lecture 5, 10/08/12

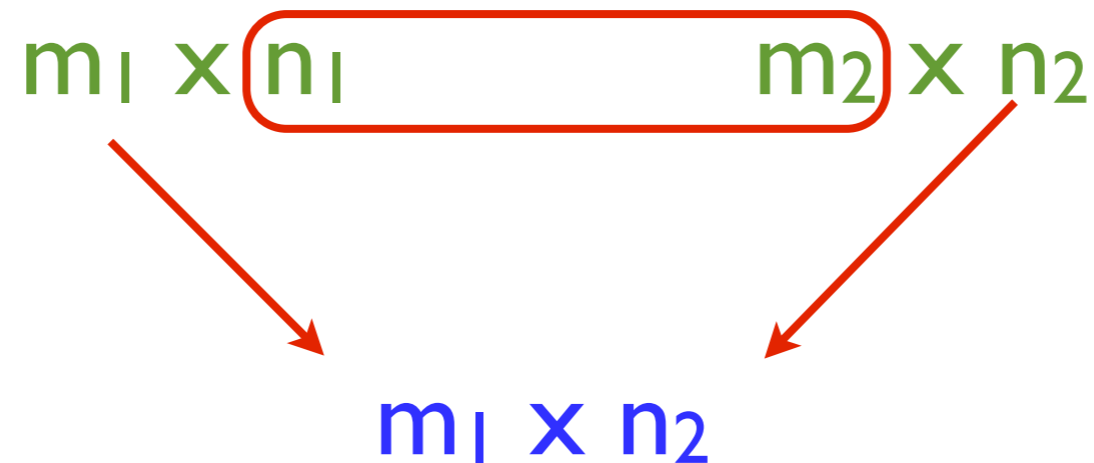
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# Matrix Algebra

- Matrix / matrix multiplication
- Matrix / number multiplication
- Matrix / matrix addition and subtraction.
- Matrix division (maybe on Wed.)

# Matrix Multiplication Continued

- Let  $A$  be  $m_1 \times n_1$  and  $B$  be  $m_2 \times n_2$ .
- Then  $A \cdot B$  only makes sense if  $n_1 = m_2$ .
- The result is a matrix with dimensions  $m_1 \times n_2$



# Matrix Multiplication

$$\begin{array}{c} A \\ 3 \times 3 \\ \left[ \begin{array}{ccc} 2 & 1 & -1 \\ 0 & -2 & 3 \\ 1 & 0 & 5 \end{array} \right] \end{array} \cdot \begin{array}{c} B \\ 3 \times 2 \\ \left[ \begin{array}{cc} 1 & -2 \\ -3 & 0 \\ -1 & 0 \end{array} \right] \end{array}$$

$$A \cdot B = \left[ \begin{array}{cc} R1 * C1 & R1 * C2 \\ R2 * C1 & R2 * C2 \\ R3 * C1 & R3 * C2 \end{array} \right]$$

# Matrix Multiplication

$$\begin{array}{c} A \\ 3 \times 3 \\ \left[ \begin{array}{ccc} 2 & 1 & -1 \\ 0 & -2 & 3 \\ 1 & 0 & 5 \end{array} \right] \end{array} \cdot \begin{array}{c} B \\ 3 \times 2 \\ \left[ \begin{array}{cc} 1 & -2 \\ -3 & 0 \\ -1 & 0 \end{array} \right] \end{array}$$

$$A \cdot B = \left[ \begin{array}{l} 2 \cdot 1 + 2 \cdot (-3) + (-1) \cdot (-1) \\ R2 * C1 \\ R3 * C1 \end{array} \quad \begin{array}{l} R1 * C2 \\ R2 * C2 \\ R3 * C2 \end{array} \right]$$

# Matrix Multiplication

- Be careful. Matrix multiplication does not commute.

$$A \cdot B \neq B \cdot A$$

# Matrix / Vector Formulation of a System

$$\begin{bmatrix} 2 & 1 & -1 \\ 0 & -2 & 3 \\ 1 & 0 & 5 \end{bmatrix} \cdot \begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} 3 \\ -2 \\ 16 \end{bmatrix}$$

$A$   $\vec{x}$   $\vec{b}$

$$2x_1 + x_2 - x_3 = 3$$

$$-2x_2 + 3x_3 = -2$$

$$x_1 + 5x_3 = 16$$

# Notation and Conventions

$$A \cdot \vec{x} = \vec{b}$$

- $A$  - is referred to as the coefficient matrix.
- $\vec{\square}$  - is a notation indicating a vector
- $\vec{x}$  - is called the vector of unknowns
- $\vec{b}$  - is called the constant vector



# Matrix Algebra Continued

# Matrix \ Number Multiplication

$$\# \cdot \begin{bmatrix} 2 & 1 & -1 \\ 0 & -2 & 3 \\ 1 & 0 & 5 \end{bmatrix} = \begin{bmatrix} \# \cdot 2 & \# \cdot 1 & \# \cdot -1 \\ \# \cdot 0 & \# \cdot -2 & \# \cdot 3 \\ \# \cdot 1 & \# \cdot 0 & \# \cdot 5 \end{bmatrix}$$

- Exactly what you would think it is.
- No restriction on dimension of matrix.

# Example

$$12 \cdot \begin{bmatrix} 2 & 1 & -1 \\ 0 & -2 & 3 \\ 1 & 0 & 5 \end{bmatrix} = \begin{bmatrix} 12 \cdot 2 & 12 \cdot 1 & 12 \cdot -1 \\ 12 \cdot 0 & 12 \cdot -2 & 12 \cdot 3 \\ 12 \cdot 1 & 12 \cdot 0 & 12 \cdot 5 \end{bmatrix}$$

# Matrix Addition

- You can add two matrices only if they are the exact same size.
- Let **A** and **B** both be **m x n**.

$$\begin{bmatrix} 0 & -3 & 2 \\ 5 & -4 & 6 \\ 1 & -1 & 2 \end{bmatrix} + \begin{bmatrix} -2 & 4 & 1 \\ 0 & 1 & 0 \\ 3 & 6 & -2 \end{bmatrix} = \begin{bmatrix} 0 + (-2) & -3 + 4 & 2 + 1 \\ 5 + 0 & -4 + 1 & 6 + 0 \\ 1 + 3 & -1 + 6 & 2 + (-2) \end{bmatrix}$$

# What we've covered

- Matrix / matrix multiplication
- Matrix / matrix addition
- Matrix / number multiplication

# What's Left?

- Matrix “division”.
- Division is really just multiplication by an **inverse**.

$$\frac{5}{3} = \frac{1}{3} \cdot 5 = 3^{-1} \cdot 5$$

- You would call **1/3** the inverse of **3**.

# What is an inverse?

- The number you multiply by to get 1.

$$2^{-1} = \frac{1}{2} \longrightarrow 2 \cdot \frac{1}{2} = 1$$

$$(-6)^{-1} = \frac{1}{-6} \longrightarrow (-6) \cdot \frac{1}{-6} = 1$$

$$(\pi)^{-1} = \frac{1}{\pi} \longrightarrow (\pi) \cdot \frac{1}{\pi} = 1$$

# The Identity

- In regular algebra / arithmetic , 1 is referred to as the **identity**.
- Multiplying by it does not change anything.

$$z \cdot 1 = z$$



# Identity Matrix

- We need to first define the concept of an **identity matrix**

- Define

$$\mathbb{I} = \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix}$$

- Then for any matrix **A** that is the proper size  $A \cdot \mathbb{I} = A = \mathbb{I} \cdot A$

# Example

$$\begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \cdot \begin{bmatrix} 9 & -2 & 0 \\ -3 & 16 & 7 \\ 0 & 4 & -1 \end{bmatrix} = \begin{bmatrix} 9 & -2 & 0 \\ -3 & 16 & 7 \\ 0 & 4 & -1 \end{bmatrix}$$

$$\begin{bmatrix} 9 & -2 & 0 \\ -3 & 16 & 7 \\ 0 & 4 & -1 \end{bmatrix} \cdot \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} = \begin{bmatrix} 9 & -2 & 0 \\ -3 & 16 & 7 \\ 0 & 4 & -1 \end{bmatrix}$$

# Identity Matrix

- The **identity matrix** is defined to be an  $n \times n$  matrix that has **ones on the diagonal** and **zeros everywhere else**.

# Matrix inverse

- Let  $A$  be a matrix. Then the **multiplicative inverse** of  $A$  is defined to be the matrix that satisfies

$$A^{-1} \cdot A = \mathbb{I} = A \cdot A^{-1}$$

- Notice,  $A$  must be a square matrix, i.e.  $n \times n$ .
- If it is not, both multiplications are not defined.

# What can we do with an inverse?

- Suppose you have a linear system posed as

$$A \cdot \vec{x} = \vec{b}$$

- Then multiply both sides by the inverse

$$A^{-1} \cdot A \cdot \vec{x} = A^{-1} \cdot \vec{b}$$

$$(A^{-1} \cdot A) \cdot \vec{x} = A^{-1} \cdot \vec{b}$$

$$(I) \cdot \vec{x} = A^{-1} \cdot \vec{b}$$

$$\boxed{\vec{x} = A^{-1} \cdot \vec{b}} \text{ Solution}$$

# Why is this useful?

- If you need to solve a system once, Gaussian Elimination is more efficient than this method.
- If you need to do so many times, this is more efficient.
- You can precompute  $A^{-1}$  once, then multiply by it when needed.

# How do we compute and Inverse?

- Let  $A$  be an  $n \times n$  square matrix.
- Form the augmented matrix  $[ A \mid I ]$
- Then row reduce to  $[ I \mid A^{-1} ]$

# Example

- Compute the inverse of  $A = \begin{bmatrix} 1 & 2 & 3 \\ 2 & 5 & 3 \\ 1 & 0 & 8 \end{bmatrix}$

- Step I  $\begin{bmatrix} A & I \end{bmatrix} = \left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right]$



# Step 2

- Use **Gaussian Elimination** to row reduce the left side.
- The right side is just along for the ride

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} \textcircled{1} & \uparrow 2 & \uparrow 3 & 1 & 0 & 0 \\ 2 & \textcircled{5} & 3 & 0 & 1 & 0 \\ \downarrow 1 & \downarrow 0 & \textcircled{8} & 0 & 0 & 1 \end{array} \right]$$

# Example Continued

- $-2*R_1 + R_2$  ;  $-2*R_1 + R_3$

$$\left[ \begin{array}{ccc|ccc} \textcircled{1} & 2 & 3 & 1 & 0 & 0 \\ 2 & 5 & 3 & 0 & 1 & 0 \\ 1 & 0 & 8 & 0 & 0 & 1 \end{array} \right]$$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & -2 & 5 & -1 & 0 & 1 \end{array} \right]$$

# Example Continued

- $2 * R_2 + R_3$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & -2 & 5 & -1 & 0 & 1 \end{array} \right]$$



$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 2 & 1 \end{array} \right]$$

# Example Continued



**-1 \* R1**

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & -1 & -5 & 2 & 1 \end{array} \right]$$



$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$

# Example Continued

- $3 \cdot R_3 + R_2$  ;  $-3 \cdot R_3 + R_1$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 3 & 1 & 0 & 0 \\ 0 & 1 & -3 & -2 & 1 & 0 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$



$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 0 & -14 & 6 & 3 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$

# Example Continued



$-2 \cdot R_2 + R_1$

$$\left[ \begin{array}{ccc|ccc} 1 & 2 & 0 & -14 & 6 & 3 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$



$$\left[ \begin{array}{ccc|ccc} 1 & 0 & 0 & -40 & 16 & 9 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$

# Example Continued

$$\left[ \begin{array}{ccc|ccc} & \mathbb{I} & & & A^{-1} & \\ 1 & 0 & 0 & -40 & 16 & 9 \\ 0 & 1 & 0 & 13 & -5 & -3 \\ 0 & 0 & 1 & 5 & -2 & -1 \end{array} \right]$$

$$A^{-1} = \begin{bmatrix} -40 & 16 & 9 \\ 13 & -5 & -3 \\ 5 & -2 & -1 \end{bmatrix}$$

- You can verify that  $A^{-1} \cdot A = A \cdot A^{-1} = \mathbb{I}$

# Recap

- Given an  $n \times n$  matrix  $A$ 
  - Step 1: Form  $[ A \mid I ]$
  - Step 2 : Reduce the left side to **reduced row echelon form**  $[ I \mid A^{-1} ]$
- Read off the inverse.



# Caveats

- Not all matrices are invertible.
- A matrix must be square to be invertible.
- However, even some square matrices are not invertible.
- If the matrix has no inverse, Gaussian Elimination will simply fail

# Example

$$\left[ \begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 2 & 4 & -1 & 0 & 1 & 0 \\ -1 & 2 & 5 & 0 & 0 & 1 \end{array} \right]$$



$$\left[ \begin{array}{ccc|ccc} 1 & 6 & 4 & 1 & 0 & 0 \\ 0 & -8 & -9 & -2 & 1 & 0 \\ \boxed{0} & \boxed{0} & \boxed{0} & -1 & 1 & 1 \end{array} \right]$$

- The left side cannot be turned into the identity!
- So this matrix is not invertible.